

MDP 212 Mechanics of Machines

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1/6

1.1 Examine this chain regarding whether it is constrained, locked or unconstrained.

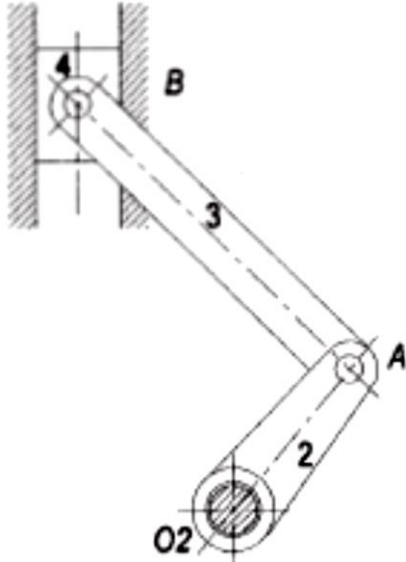


Figure.1

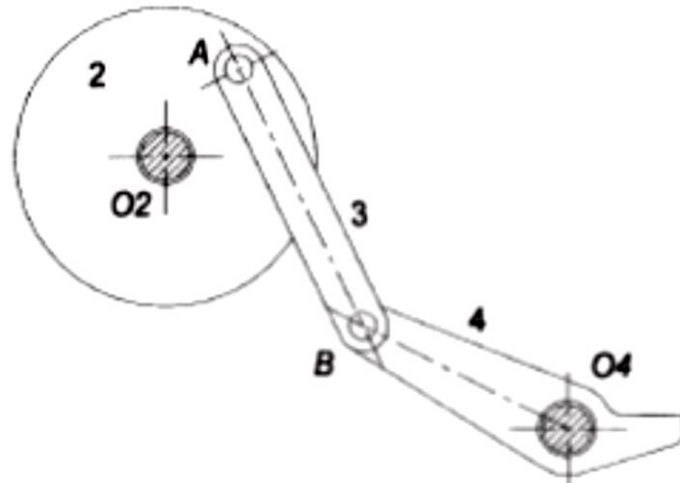


Figure.2

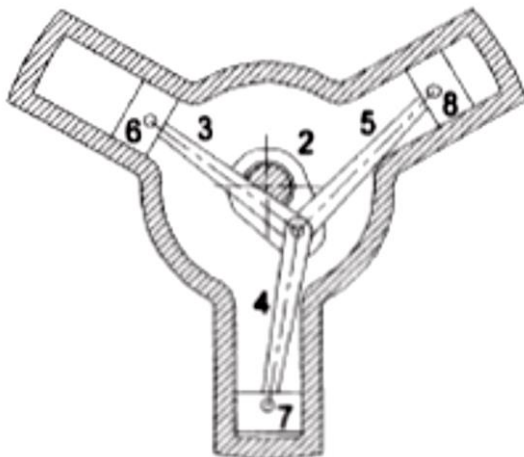


Figure.3

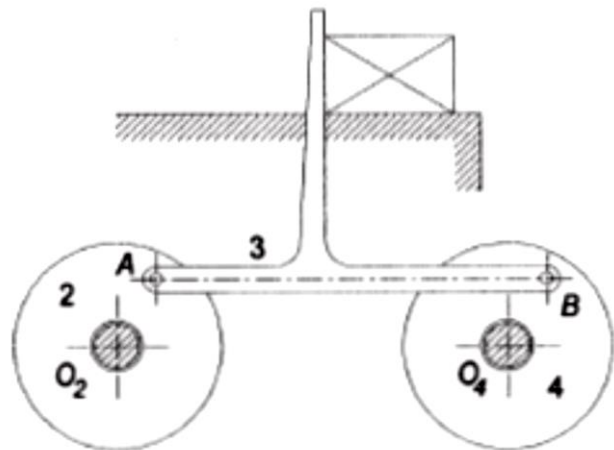


Figure.4

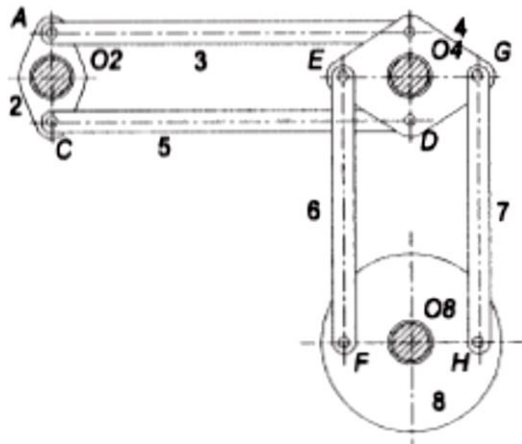


Figure.5

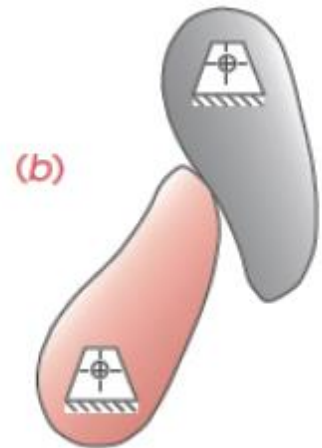


Figure.6

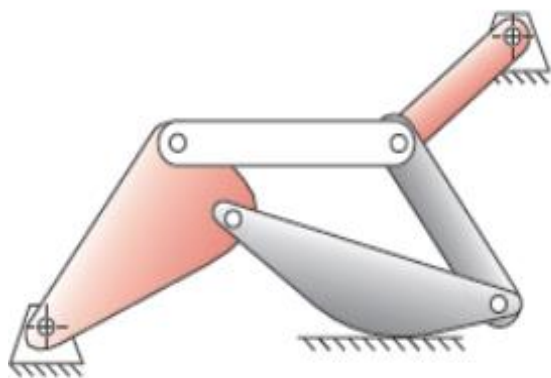


Figure.7

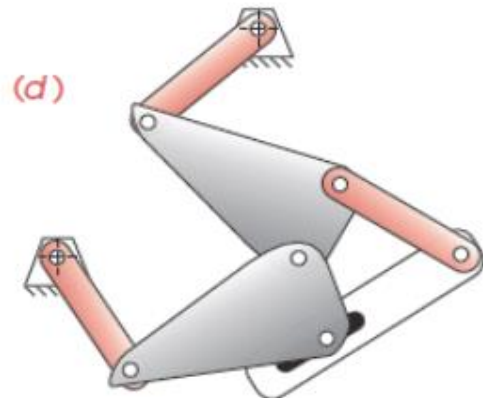


Figure.8

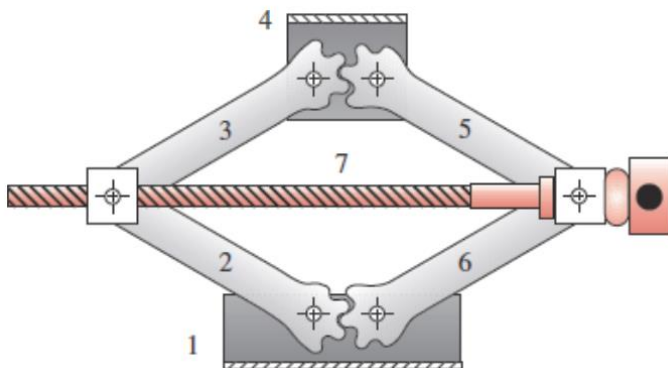


Figure.9

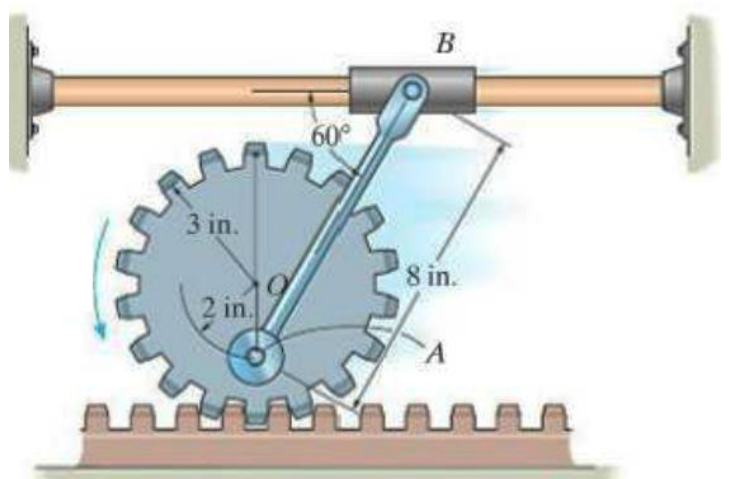


Figure.10

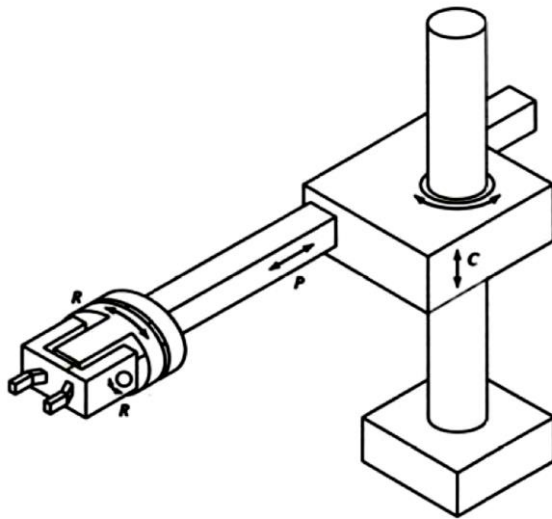


Figure.11

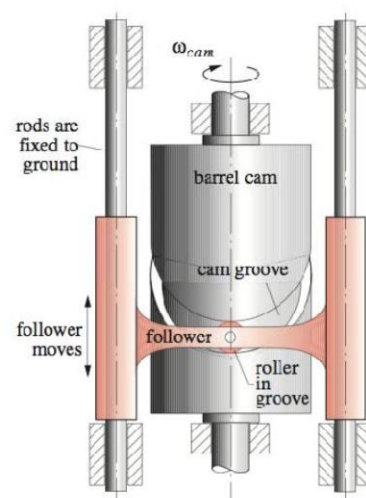


Figure.12

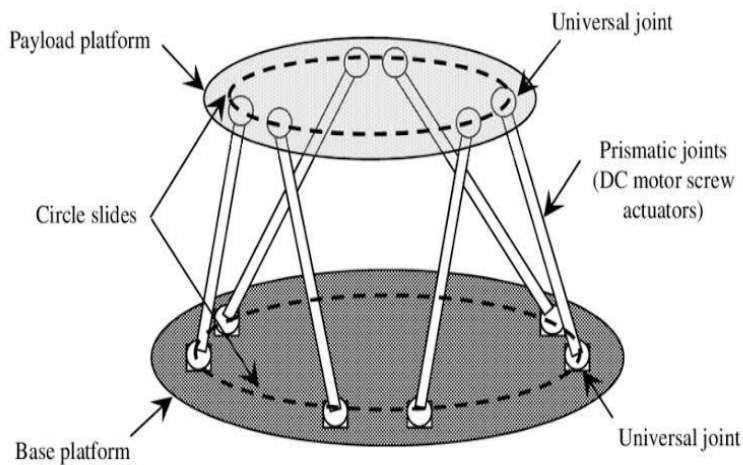


Figure.13

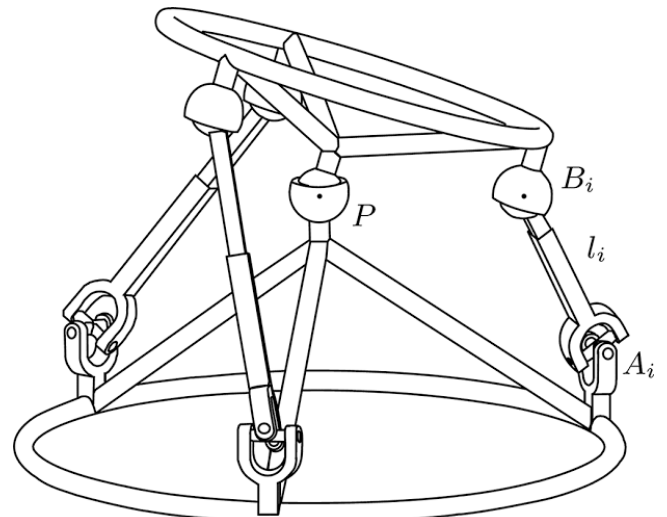


Figure.14

- 1.2 Figure.15 shows a hacksaw, used for material cutting. Sketch the dynamic diagram, and so determine the degrees of freedom.

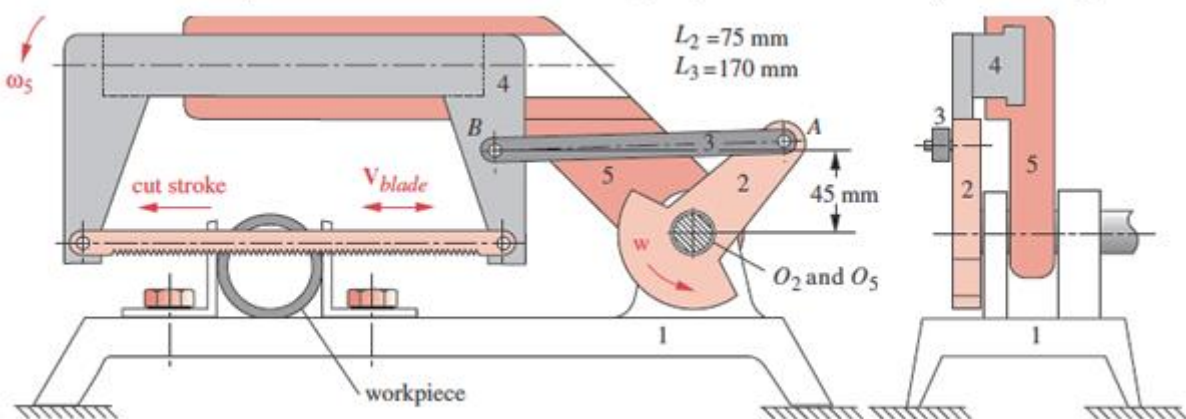


Figure.15

- 1.3 Calculate the Grashof condition of the fourbar chains defined below. State the possible fourbar mechanisms which can be generated from each chain. The lengths of the links are as following.

- a. 20, 45, 70, 90.
- b. 20, 35, 70, 90.

- 1.4 In the four-bar mechanism shown in Figure.16, axes O and Q are fixed. Determine its type. If the link (2), which is the driver, turns C.C.W., find the two extreme positions of QB and the angle through which link (4) oscillates.

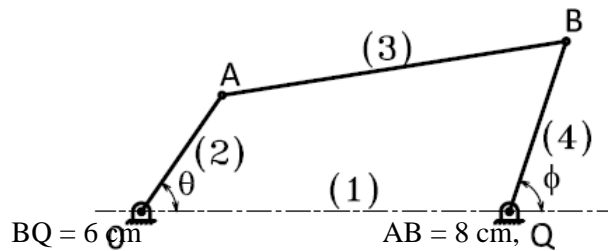


Figure.16

OA = 4 cm,
QO = 8 cm.

- 1.5 In the four-bar mechanism shown in Figure.17, axes O and Q are fixed. Prove that it is a crank-lever four-bar mechanism and name its crank. Determine the two extreme positions of the lever and the angle through which it oscillates.

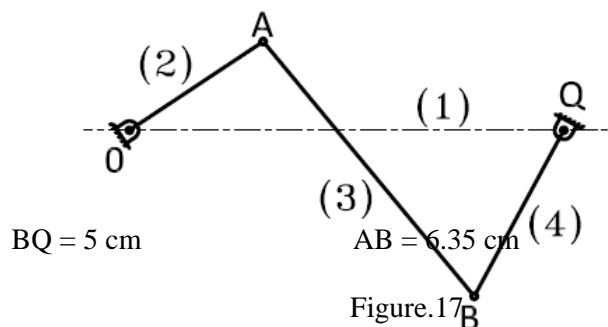


Figure.17

OA = 4 cm
QO = 5.5 cm

- 1.6 In the mechanism shown in Figure.18, block (4) slides in a slot in the fixed frame (1). Axis O of crank (2) is fixed on (1). Find the two extreme positions of B, the axis of the pin by which link (3) is attached to the block (4), and the length of the stroke of the block (4).

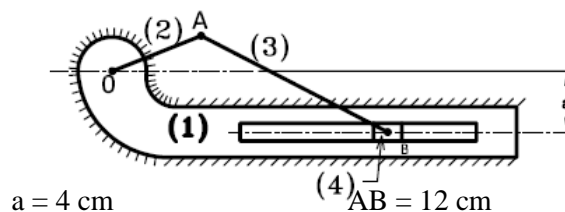


Figure.18

OA = 4 cm

- 1.11 In the Davis steering-gear shown in Figure.23, the stub axles CA and DB are pivoted at A and B on the rigid axle and are continuous with the arms AG and BH respectively. The cross link EF is pivoted at the ends to the blocks sliding on the arms AG, BH and slides in the guides at M & N. Show that correct steering is obtained if the distance between front and rear axles is $(ac/2b)$.

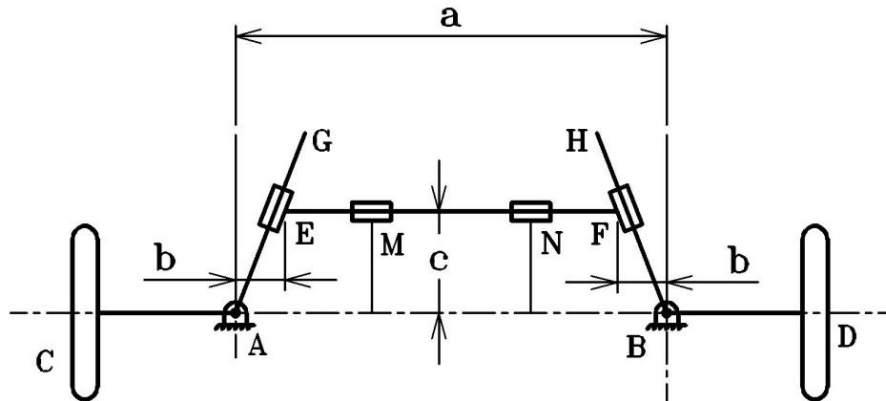


Figure.23

- 1.12 The Ackermann steering gear shown in Figure.24, consists of a four-bar mechanism in which the links AK and CL are equal in length, and are rigidly connected to the stub axles of the two front wheels. In the mid-position, when the car is moving along a straight path, KL is parallel to AC, while AK and CL are inclined to the longitudinal axis of the car by an angle $\alpha = 18^\circ$. Find the angle to which the left front wheel turns when the right front wheel turns 30° to the right (i.e. C.W.).

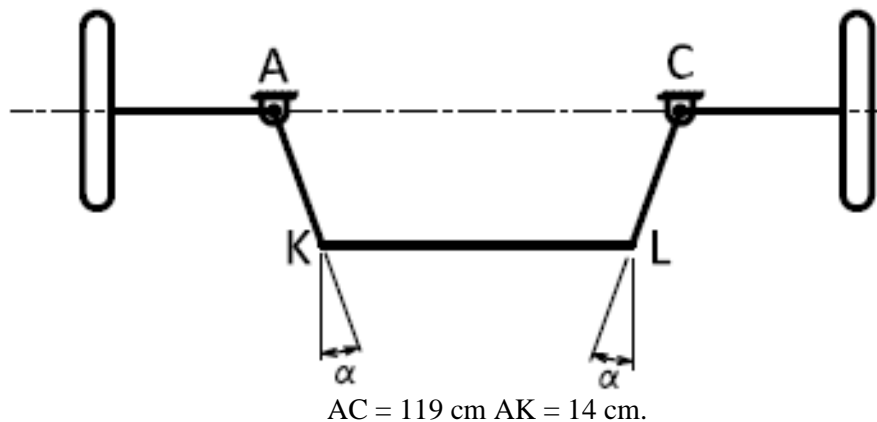


Figure.24

- 1.13 Two shafts, the axes of which intersect, are coupled by Hooke's joint. The driving shaft rotates uniformly and the total variation in speed of the driven shaft is not to exceed 8% of the mean speed. What is the greatest possible inclination of the center lines of the shafts?
- 1.14 Two parallel shafts are connected by an intermediate shaft inclined at an angle α to both. Two Hooke's joints are used for connecting the intermediate shaft with both shafts. Find the ratios of the angular velocities of the two parallel shafts when the forked ends of connecting shafts are:
- In the same plane.
 - In the planes at right angles.